

#### MAIN FEATURES

This board is used when it is necessary to adjust encoder electronic features to control ones. Main functions of EMB are output signal splitting and adaptation of output stages.

For instance, it happens to have an encoder with 5 V DC output and a control that accepts only 24 V DC inputs. It may also happen to use an encoder connected with a control with the same power supply, but different electronics.

It can solve a wide range of problems: check the ordering code to find further informations.

On the board there can be up to 2 different voltages and it must be supplied through the X4 connector with the higher voltage used. Moreover it is possible to obtain up to 8 outputs from the same input by assembling several boards in a single support in order to reduce wirings drastically.

In this case the ordering code will contain informations about all outputs.





			Г	in	Г	out1	Г	out2 (optional	max 8)	
ORDERING CODE	EMB	*0	5	Ľ	8/24	P	8/24	P	. 2V	. XXX
si	SERIES ignal splitter EMB INPUT dd for optically isolate INPUT VOLTA (mod. EMB) (mod INPUT E (mod	( OPTION ed input () GE X1 CO ) 8 24 V . EMBO) 24 LECTRON od. EMB) N	NNECTOR 5 V DC 5 7 DC 8/24 4 V DC 24 ICS X1 CO (mod. EN UTAGE (OU (mod. EME (mod. T ELECTRI	IB) NPN N Ollector C sh-pull P e driver L IB) PNP R T1) X2 COI 1) 8 24 V 1. EMBO) 24 DNICS (OU NICS (OU UTPUT VOI	NNECTOR 5 V DC 5 7 DC 8/24 1 V DC 24 T1) X2 COI (mod. EME (mod. trage (OU) (mod. EME (mod. T ELECTR(	NNECTOR IB) NPN N ollector C sh-pull P e driver L T2) X3 CO s) 8 24 V 1. EMBO) 2- DNICS (OU	NNECTOR 5 V DC 5 / DC 8/24 4 V DC 24 T2) X3 C0 (mod. EN IPN open c pt	NNECTOR AB) NPN N ollector C ish-pull P e driver L	/ERSION on 2 .2V	
The following example may explain better a typical EMB application:								C	ustom vei	VARIANT rsion XXX

The following example may explain better a typical EMB application: an encoder with 5 V DC RS-422 output has to be connected to a 24 V DC push-pull input and also to an instrument with 5 V DC RS-422 input. Ordering code will be: **EMB5L8/24P5L** where

EMB5L indicates 5 V DC line driver input on X1 connector EMB5L8/24P indicates 24 V DC push-pull output on X2 connector EMB5L8/24P5L indicates 5 V DC line driver output on X3 connector

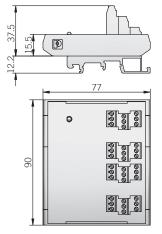
Power supply of this board is 24 V DC, because it is the highest used value, and it will be supplied through X4 connector.

Eltra



### EMB

Single implementation



#### Multiple implementation (4 modules / 8 outputs max) 90 90 90 90 o ø •

dimensions in mm

## ELECTRICAL SPECIFICATIONS

ELECTRICAL OF LOTTICA	nono	
Power supply	5 = 4,5 5,5 V DC 8/24 = 7,6 25,2 V DC 24 = 22,8 25,2 V DC	
Current consumption without load on X4	70 mA max	
Supply current on X1 (for sensor power supply)	100 mA max	
Max current consumption	Imax = 280 + 960 + 100 = 1340 mA considering: 4 x EMB = 70 x 4 = 280 mA 3 x 8 outputs (40mA each) = 960 mA 1 x input sensor supply current = 100 mA	
Output type *	NPN / NPN open collector / push-pull / line driver	
Electromagnetic compatibility	according to 2014/30/EU directive	
RoHS	according to 2011/65/EU directive	
UL / CSA certificate	E212495	

\* for further details please see OUTPUT LEVELS under TECHNICAL BASICS section

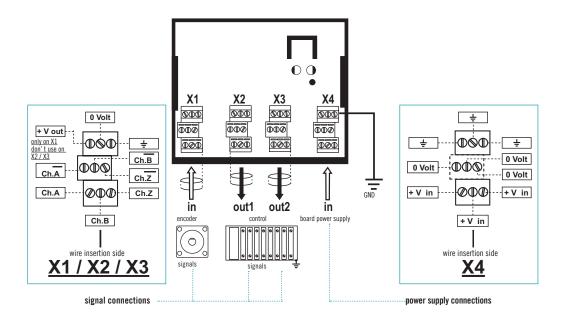
MECHANICAL SPECIFIC	ATIONS
Enclosure rating	IP00
Operating temperature	-20° +85°C (-4° +185°F)
Storage temperature	-20° +85°C (-4° +185°F)
Fixing type	DIN 46277-3 rail (Omega) DIN 46277-2 rail (Omega)
Weight	150 g (5,29 oz) (1 module)

X1 INPUT ELECTRONIC SPECIFICATIONS					
Input type	Max load current (mA per channel)	Max input frequency (kHz)*			
5P (TTL compatible)	15	100			
5L (RS-422 compatible)	40	200			
8/24P (push pull)	20	100			
8/24L (line driver HTL)	20	100			
8/24N (NPN)	20	10			
8/24C (NPN open coll)	20	10			
8/24R (PNP)	20	10			

\* depending on length and cable specs



# **TERMINAL BOARD CONNECTIONS**



# **APPLICATION EXAMPLES**

