

# **Model Number**

CE

## TOPSCAN2-8-HS-2500-2/L900/38a

E 1

Active infrared scanner Profile length 900 mm

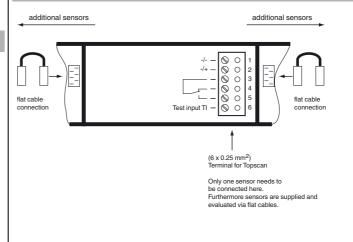
#### **Features**

- Moving presence sensor for swing doors
- Configurable for a wide range of door ٠ leaf widths
- Each beam can be adjusted individu-• ally
- Selectable background suppression and evaluation
- Beam adjustment to closing edge width
- Test input .
- Double-beam version .

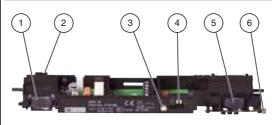
## **Product information**

The TopScan2 series is a modular sensor system that can be used in a flexible manner for various requirements relating to the monitoring of automatic doors. The system can be mounted for either static or mobile use. The housing can be easily shortened and up to five sensor modules can be arranged side by side, whereby each beam can be configured individually. When it comes to the operating modes, there is the choice between background suppression and background evaluation. The light or dark switching modes, detection range and closing edge alignment can also be adjusted. These features make the TopScan2 active infrared scanner ideal for use with a wide range of automatic door systems.

## **Electrical connection**



## Indicators/operating means



| 1 | Transmitter                  |
|---|------------------------------|
| 2 | Adjuster for monitoring edge |
| 3 | Functional display           |
| 4 | Programming switch           |
| 5 | Receiver                     |
| 6 | Detection range adjuster     |

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Refer to "General Notes Relating to Pepperl+Fuchs Product Information" USA: +1 330 486 0001 fa-info@us.pepperl-fuchs.com

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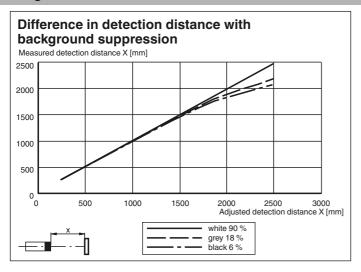


| Technical data                    |                |  | Typical applications  |  |  |
|-----------------------------------|----------------|--|---|--|--|
| General specifications            |                | - Dretestion mechanism for electron educe  |   |  |  |
| Detection range min.              |                | 0 1500 mm by background evaluation,<br>500 1500 mm by background suppression   | <ul> <li>Protection mechanism for closing edges<br/>on automatic sliding doors and revolving<br/>doors</li> <li>Anti-collision protection for people/objec<br/>in the vicinity of revolving doors</li> <li>Edge and pinch protection for sliding door</li> <li>Entry monitoring for buses and trains ope<br/>rated within the public transportation net-</li> </ul> |  |  |
| Detection range max.              |                | 0 2500 mm with background evaluation,<br>500 2500 mm with background suppression   |   |  |  |
| Light source                      |                | IRED   |   |  |  |
| Black/White difference (6 %/90 %) |                | < 20 % at 2000 mm sensor range   |   |  |  |
| Marking                           |                | CE   |   |  |  |
| Number of beams                   |                | 2 (number of built-in sensor modules AIR)  |   |  |  |
| Operating mode                    |                | switching between background suppression/evaluation  | work  |  |  |
| Diameter of the light spot        |                | 75 x 75 mm by sensing range 2000 mm  |   |  |  |
| Indicators/operating means        |                |  | Detection area  |  |  |
| Function indicator                |                | LED red  |   |  |  |
| Control elements                  |                | Sensing range adjuster, light-on/dark-on changeover switch,<br>changeover switch for mode of operation Background suppres-<br>sion / Background evaluation ; Adjuster for edge monitoring left/<br>right |   |  |  |
| Factory setting                   |                | Background suppression   |   |  |  |
| Electrical specifications         |                |  |   |  |  |
| Operating voltage                 | UB             | 17 30 V DC , 18 28 V AC  |   |  |  |
| No-load supply current            | I <sub>0</sub> | < 100 mA   |   |  |  |
| Input                             | 0              |  |   |  |  |
| Test input                        |                | emitter deactivation with U = $17 \dots 30$ V DC only in background evaluation mode of operation and DC operation  |   |  |  |
| Output                            |                |  |   |  |  |
| Switching type                    |                | Light-on/dark-on changeover switch   |   |  |  |
| Signal output                     |                | Relay, 1 alternator  |   |  |  |
| Switching voltage                 |                | max. 24 V DC , 48 V AC   |   |  |  |
| Switching current                 |                | ≤1 A   |   |  |  |
| Switching power                   |                | 24 W / 55 VA   |   |  |  |
| Response time                     |                | 30 ms , 2 s after test   |   |  |  |
| Ambient conditions                |                |  |   |  |  |
| Ambient temperature               |                | -20 60 °C (-4 140 °F)  | Accessories   |  |  |
| Mechanical specifications         |                |  |   |  |  |
| Housing length L                  |                | 900 mm   | AIR16   |  |  |
| Mounting height                   |                | max. 2500  | Sensor module   |  |  |
| Degree of protection              |                | IP52   |   |  |  |
| Connection                        |                | screw terminals  | LAGERBOCK AIR16   |  |  |
| Material                          |                |  | Pedestal for the sensor module AIR16  |  |  |
| Housing                           |                | aluminum / ABS   | TonSoon & Coble Leon Bosie  |  |  |
| Optical face                      |                | PC   | TopScan-S Cable Loop Basic  |  |  |
| Mass                              |                | approx. 650 g  | Metal cable protector   |  |  |
| Compliance with standards a       | nd direct      |  | TopScan2 Cable 300 mm   |  |  |
| Ves                               |                |  | Ribbon cable for connecting sensor m  |  |  |
| Directive conformity              |                |  | -   |  |  |
| EMC Directive 2004/108/EC         |                | EN 61000-6-2:2005 EN 61000-6-3:2007  | dules   |  |  |
| Standard conformity               |                |  | TopScan-S Cap Set   |  |  |
| Standards                         |                | EN 62471:2008  | End cover for TopScan-S aluminum pro  |  |  |
| Approvals and certificates        |                |  | le section  |  |  |

## Approvals and certificates

CCC approval UN/ECE Regulation No. 10 (E1)

## **Curves/Diagrams**



TopScan-S Profile L1400

TopScan-S Gasket IP54

Housing seal TopScan-S

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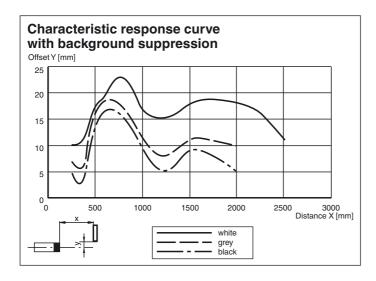
CCC approval / marking not required for products rated ≤36 V

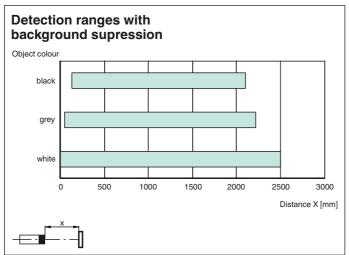
Type-approval number: 047349

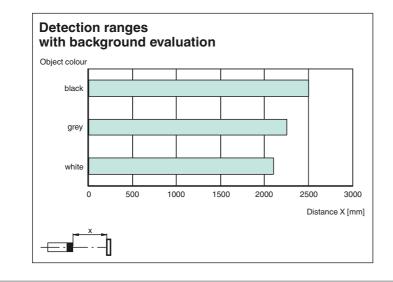
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**Operating principle** 

The two large-area lenses (one for the infrared transmitter and one for the two photodiode receivers with ambient light filter) have an optical center-to-center distance of approx. 150 mm, resulting in a light spot size of 75 mm x 75 mm. The angle of the two lens systems can be adjusted to each other via a precision gear according to the principle of background/foreground suppression. Such precisely defined focal lengths enable a precision detection range setting of up to 2500 mm.

The detection range can be extended up to 2500 mm and responds to any object in the detection area, with minimal effect from the surface color and structure. Reflection levels that exceed the specified maximum detection range are not detected by the sensor, even with highly reflective objects - for example corrugated aluminum plates or marble floors (with background suppression). The detection fields of several devices can be overlapped without interference.

#### **Background Suppression Operating Mode**

In this operating mode, the background is "detected" but not actually evaluated (ignored). A reflection signal from an object within the specified detection area is required as a switching signal.

#### **Background Evaluation Operating Mode**

The TopScan2 can also be used with a test option, regardless of whether or not there is an object/person in the detection area. The receiver con-

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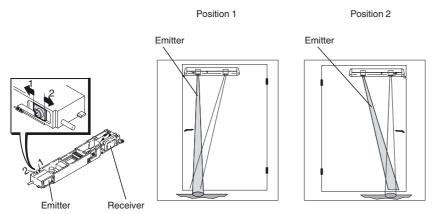


stantly sees the reflected light from the transmitter when the background is present. Testing is performed by disconnecting the transmitter from the supply voltage.

The background is used as a reflector. If the light beam is broken by an object, a switching signal is triggered.

#### **Configuration information**

## **Configuring the Monitoring Edge**

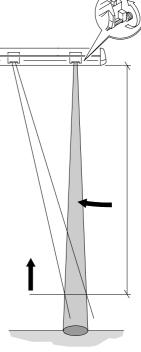


The transmitter of each sensor features two beam position settings via which the monitoring edge can be aligned to the left or to the right.

## **Detection range setting:**

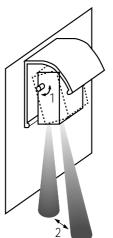
- 1. Rotate the adjustment screw counter-clockwise until the LED illuminates
- 2. Slowly rotate the adjustment screw clockwise until the LED goes out
- 3. Then rotate the adjustment screw further by 1/8 of a rotation





# Angle settings:

By rotating the sensor around its rotational axis (1), the offset (2) of the detection point to the wall can be easily changed. The angle setting can be continuously adjusted from 0° to 30°.



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### **Programming:**

Both the switching mode and the operating mode can be configured via the programming switch for each sensor.

Test input (TE) — background suppression operating mode

| TE     | Switching mode | LED                 | Signal output |
|--------|----------------|---------------------|---------------|
| Active | Light          | Does not illuminate | Closed        |
| Active | Dark           | Does not illuminate | Open          |

Note: only if there is an object in the detection area

Test input (TE) — background evaluation operating mode

| TE     | Switching mode | LED         | Signal output |
|--------|----------------|-------------|---------------|
| Active | Light          | Illuminates | Open          |
| Active | Dark           | Illuminates | Closed        |

Note: Regardless of whether or not there is an object in the detection area

#### Light On Switching Mode (H)

A light scanner's output is switched on (activated) if the receiver detects "light", i.e. there is an object in the operating range.

## Dark On Switching Mode (D)

A light scanner's output is switched on (activated) if the receiver detects "dark", i.e. there is no object in the operating range.

Programming switch

|     | Left (1)               | Right (2) |
|-----|------------------------|-----------|
| Off | Background suppression | Dark on   |
| On  | Background evaluation  | Light on  |

