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Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

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60

Distance X [mm]

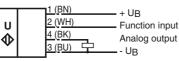
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# **Electrical Connection**

#### Standard symbol/Connections:



Core colors in accordance with EN 60947-5-2.

### Pinout



Wire colors in accordance with EN 60947-5-2

1	BN	(brown)
2	WH	(white)
3	BU	(blue)
4	BK	(black)

# **Accessories**

BF 5-30

Universal mounting bracket for cylindrical sensors with a diameter of 5 ... 30 mm

## **BF 12**

Mounting flange, 12 mm

#### **BF 12-F**

Mounting flange with dead stop, 12 mm

V1-G-2M-PVC Female cordset, M12, 4-pin, PVC cable

V1-W-2M-PUR

Female cordset, M12, 4-pin, PUR cable

### **Functional description**

This sensor is used to measure the thickness of objects. It teaches itself by independently switching to a reference object. The distance h to this object serves as a reference distance and defines the object thickness 0 mm. This reference distance can be dynamically tracked in order to compensate for external influences. This guarantees a high measurement accuracy of the sensor over the entire temperature range.

### Automatic teach-in process

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Immediately after the supply voltage is connected, the sensor automatically references itself to the reference object and teaches in the distance as the reference distance. The distance h between the sensor surface and the reference object must lie within the valid range for the reference distance (see Technical Data). The sensor then immediately reverts to normal operation.

If no reference object is detected, the red LED flashes (Fault).

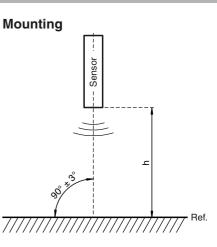
# Normal operation

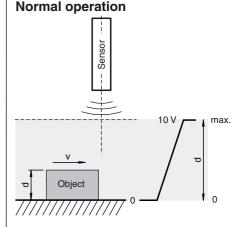
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# **Additional Information**





In normal operation, the sensor outputs a value at the analog output, which is proportional to the thickness of the object. The object thickness 0 mm (measurement to the reference object) is represented in this by the minimum analog value and the largest measurable object thickness (see Technical Data) is represented by the maximum analog value.

## Dynamic tracking of the reference distance

The dynamic tracking of the reference distance can be activated and deactivated by means of the function input circuitry (see Function Input).

### Dynamic tracking activated:

#### (Function input open or connected with $-U_B$ )

When measuring an object, the sensor must detect the reference point again within no longer than four seconds in order to be re-referenced to it. Otherwise the object is interpreted as the reference. Then, in accordance with a PTI characteristic with a time constant of 14 s, this distance value becomes the new reference distance.

If the object is incorrectly taught-in as the reference and then moves outside the sensor's detection field so that the greater distance to the actual reference object is measured, the sensor immediately reacts. The new, greater distance is taught-in as the reference without delay.

### Dynamic tracking deactivated:

(Function input connected with  $+U_B$ )

The reference distance automatically taught-in when the sensor is switched on is retained during the entire operation.

### **Function input**

The function input is used to activate/deactivate the dynamic tracking of the reference distance (see above).

### LED indicator

Indication as a function of operating status	Red LED	Yellow LED
Teach-in control limit:		
No reference object detected or reference object at an	Flashes	Off
incorrect distance		
Normal operation		
Measurement on object	Off	On
Measurement on reference	Off	Off
Fault	On	Last valid status

### Installation conditions

If the sensor is installed at places, where the environment temperature can fall below 0 °C, for the sensors fixation, one of the mounting flanges BF 12, BF 12-F or BF 5-30 must be used. In case of direct mounting of the sensor in a through hole, it has to be fixed at the middle of the housing thread.

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