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## Model Number

PMI90DV-F130-I2E2-V15

## Features

- Analog position indicator with end position monitoring
- 2 configurable switching frames
- Preset range of angle measurement 0 ... $90^{\circ}$
- Extended analog signal range

| Technical data |  |
| :---: | :---: |
| General specifications |  |
| Measurement range | $\begin{aligned} & \max .180^{\circ} \\ & \min .90^{\circ} \end{aligned}$ |
| Adjustment range | $180^{\circ}$, 2 switch frames programmable |
| Nominal ratings |  |
| Operating voltage $U_{B}$ | $18 . .30 \mathrm{~V}$ DC |
| Reverse polarity protection | reverse polarity protected |
| Repeat accuracy | $\pm 0.25{ }^{\circ}$ |
| Resolution | $0.2{ }^{\circ}$ |
| Temperature drift | $0.02{ }^{\circ} /{ }^{\circ} \mathrm{C}\left(-25^{\circ} \mathrm{C} . .70^{\circ} \mathrm{C}\right)$ |
| No-load supply current $\mathrm{I}_{0}$ | $\leq 45 \mathrm{~mA}$ |
| Functional safety related parameters |  |
| MTTF $_{\text {d }}$ | 234 a |
| Mission Time ( $\mathrm{T}_{\mathrm{M}}$ ) | 20 a |
| Diagnostic Coverage (DC) | 0 \% |
| Indicators/operating means |  |
| LED yellow 1 | switching state, Switching output 1 |
| LED yellow 2 | switching state, Switching output 2 |
| LED PWR/ERR | status display LED, green/red (Power on / missing actuator / keylock) |
| LED I | Activator within measuring range |
| Switching output |  |
| Output type | 2 switch outputs PNP, NO, reverse polarity protected, short-circuit protected, programmable |
| Operating current $\mathrm{I}_{\mathrm{L}}$ | $\leq 100 \mathrm{~mA}$ |
| Switching hysteresis | $1^{\circ}$ |
| Voltage drop | $\leq 3 \mathrm{~V}$ |
| Short-circuit protection | pulsing |
| Analog output |  |
| Output type | $\begin{aligned} & \text { current output } \\ & 3.8 \ldots 20.5 \mathrm{~mA}\left(\mathrm{R}_{\mathrm{L}}<400 \Omega\right) \end{aligned}$ |
| Linearity error | $\pm 1.5^{\circ}$, (with original actuator) |
| Transfer characteristics |  |
| Internal measurement cycle | 30 ms |
| Ambient conditions |  |
| Ambient temperature | $-25 \ldots 70^{\circ} \mathrm{C}\left(-13 \ldots 158^{\circ} \mathrm{F}\right)$ |
| Mechanical specifications |  |
| Connection type | 5-pin, M12 x 1 connector |
| Degree of protection | IP67 |
| Material |  |
| Housing | PBT |
| Target | mild steel, e. g. 1.0037, SR235JR (formerly St37-2) |
| Mass | 180 g |
| Compliance with standards and directives |  |
| Standard conformity |  |
| Standards | $\begin{aligned} & \text { EN 60947-5-2:2007 } \\ & \text { IEC 60947-5-2:2007 } \end{aligned}$ |

Approvals and certificates
UL approval
CCC approval
cULus Listed, General Purpose, Class 2 Power Source CCC approval / marking not required for products rated $\leq 36$ V

## Dimensions



## Electrical Connection



## Pinout



Wire colors in accordance with EN 60947-5-2

| 1 | BN | (brown) |
| :--- | :--- | :--- |
| 2 | WH | (white) |
| 3 | BU | (blue) |
| 4 | BK | (black) |
| 5 | GY | (gray) |

## Accessories

## BT-F130-A

Actuator for F130 series

## V15-G-2M-PVC

Female cordset, M12, 5-pin, PVC cable

## V15-W-2M-PVC

Female cordset, M12, 5-pin, PVC cable

## Functional Description

The inductive angular positioning system is a measuring system designed to detect the angular position of valve actuators and valves. The system is equipped with an analog output I ( $4 \mathrm{~mA} \ldots 20 \mathrm{~mA}$ ) for continuous position detection, as well as two switching outputs (S1 and S2) for monitoring the end position.
Actuator BT-F130-A is normally attached to the rotary system component to detect the position. This actuator rotates in the central hole on the sensor and contains the metal insert required for detecting the position. The component is optimally adapted to the mechanical requirements of valves and valve actuators.

## Factory Default Setting

The sensor is set at the factory to monitor a range of $0^{\circ} \ldots 90^{\circ}$. Switching output S 1 is positioned at $0^{\circ}$; switching output S 2 is positioned at $90^{\circ}$. The switching range of both switching outputs is $\pm 6^{\circ}$ around the relevant switching point.
The analog ouput has a power reserve from $-30^{\circ}$ to +30 beyond the measuring range. The lower trip value of the power reserve $\left(-30^{\circ}\right)$ is 3.8 mA . The upper trip value of the power reserve $\left(+30^{\circ}\right)$ is 20.5 mA . Beyond this power reserve, an output current of 3.6 mA is adopted.

## Behavior of the current output at a measuring range of $90^{\circ}$ :



## Programming the Measuring System (General)

For best results when adjusting the process, the measuring system can be programmed using keys $\mathrm{S} 1, \mathrm{I}$, and S 2 . If the keylock is active, it must first be deactivated. The sensor indicates that the keylock is active by changing the color of the "Power/Error" LED to red when a button is pressed. To unlock the buttons, press and hold the S1 and S2 buttons simultaneously for 3 seconds. The color of the "Power/Error" LED changes to green. The buttons are no longer locked.
Note:
When programming the monitoring area (analog output), the switching points of the two switching outputs (S1 and S2) are always automatically adopted from the start and end point of the monitoring area. If different switching points or switching windows need to be programmed, this step must always be performed after the monitoring area has been programmed.

## Programming the Monitoring Area

The monitoring area represented by the analog output can be programmed within a range of $90^{\circ} \ldots 180^{\circ}$.

1. Press and hold the I key for $>2$ seconds. The flashing yellow LED I indicates that the device is ready for the start point of the analog ramp to be programmed.
2. Move the actuator to the position you wish to define as the start point of the analog ramp. Then press the I key. The yellow LED I lights up for 2 seconds and then starts to flash again. This indicates that the device is ready for the end point of the analog ramp to be programmed.
3. Move the actuator to the position that you wish to define as the end point of the analog ramp.

Note:
When the actuator rotates, the first $30^{\circ}$ define the direction of rotation of the measurement range in which the values of the analog output increase (clockwise/counterclockwise).
4. Briefly press the I key. The setting is then stored in the nonvolatile memory of the sensor. The yellow LED I then lights up continuously to indicate that programming was successful.
The entire signal range ( $4 \mathrm{~mA} \ldots 20 \mathrm{~mA}$ ) of the analog output is scaled to the programmed angle segment.

## Note: Programming a $90^{\circ}$ Angle Segment

If an angle segment of $90^{\circ}$ is to be programmed for the analog output, you can capitalize on the fact that the angle segment must be a minimum of $90^{\circ}$. In this instance, when programming the angle segment (step 3), move the actuator to a position that is less than $90^{\circ}$ but greater than $30^{\circ}$ in relation to the starting position. When this position is confirmed by pressing the relevant key, the sensor automatically calculates and stores the position value for $90^{\circ}$.

## Note: Programming a $180^{\circ}$ Angle Segment

If an angle segment of $180^{\circ}$ is to be programmed for the analog output, you can capitalize on the fact that the angle segment must be a maximum of $180^{\circ}$. In this instance, when programming the angle segment (step 3), you can move the actuator to a position that is greater than $180^{\circ}$ in relation to the starting position. When this position is confirmed by pressing the relevant key, the sensor automatically calculates and stores the position value for $180^{\circ}$.

## Programming Different Switching Windows

The switching windows of the two switching outputs ( S 1 and S 2 ) can be configured within the monitoring area as required. The process for programming the switching window for switching output S1 is described here as an example. The switching window for switching output S2 is programmed in exactly the same way, just using the S2 key.

1. Press and hold the S 1 key for $>2$ seconds. The flashing yellow LED indicates that the device is ready for the start point of the switching
window for switching output S 1 to be programmed.
2. Move the actuator to the position you wish to define as the start point of the switching window for switching output S1.
3. Briefly press the S1 key. The yellow S1 LED lights up for 2 seconds and then starts to flash again. This indicates that the device is ready for the end point to be programmed.
4. Move the actuator to the position you wish to define as the end point of the switching window for switching output S1.

Note:
At the end of programming, the area covered by the actuator will be the angle range in which the switching output is active.
5. Briefly press the S1 key. The setting is then stored in the nonvolatile memory of the sensor. The yellow S1 LED then lights up continuously to indicate that programming was successful.

## Note:

If, in the time that elapses between the start and end points of the switching window being programmed, the actuator does not move, the smallest possible switching window is programmed with a width of $\pm 2.5^{\circ}$ around the actuator.

## Note:

If the start or end point of the switching window is less than $6^{\circ}$ from the start or end of the monitoring area, the start or end point of the switching window is automatically set at $6^{\circ}$ past the edge of the monitoring area.
Example: The edge of the monitoring area is set at $90^{\circ}$. You program the start of the switching window at $60^{\circ}$ and the end of the switching window at $85^{\circ}$. In this case, the switching range will extend from $60^{\circ}$ to $96^{\circ}$.

## Activating the keylock

The keylock is not activated initially. Press any button on the sensor briefly to determine whether the keylock is active. If the color of the "Power/ Error" LED remains green, the keylock is inactive and if the color of the "Power/Error" LED changes to red, the keylock is active. To activate the keylock, press and hold the S1 and S2 keys simultaneously for 3 seconds. The color of the "Power/Error" LED changes to red.

## Using a different actuating element

You can use a different actuator instead of the BT-F130-A actuator provided, which must be positioned centrally in the sensor opening. When using a different actuating element, the element must fulfill all requirements relating to the material, dimensions and distance to the sensitive surface on the sensors (see table). Failing to fulfill all of these requirements may reduce the accuracy/resolution of the sensor or even cause the sensor to stop functioning.

Dimensions when using a different actuating element


A Drive shaft
B Insulation ring made from non-conductive material
C Separate actuator ( $\mathrm{L} \geq 23 \mathrm{~mm}$ )
D Sensitive surface on the sensors (black, cylindrical inner surface)
E Sensor

