



Model Number

PHA500-F200A-B17-V1D

Precision positioning on hole in the 70 mm x 70 mm housing

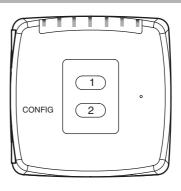
Features

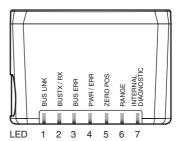
- Detects the position of an index hole
- · Large capture range
- · High operating range
- Integrated contrast compensation
- · Compact design
- PROFINET interface
- Integrated illumination

Function

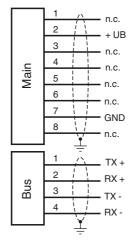
The sensor has been developed for the precision positioning of high-bay racking operating equipment. It detects circular holes in the racking structure and their positional deviation from the nominal position. The sensor operates in two dimensions.

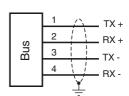
Indicating / Operating means





Electrical connection





Pinout





Technical data

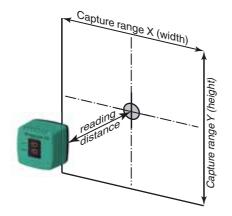
General specification
Light type

General specifications			
Light type		Integrated LED lightning (infrared)	
Object size		Hole diameter 13 mm	
Response delay		100 ms	
Read distance		500 mm	
Depth of focus		± 50 mm	
Capture range		max. 90 mm x 90 mm	
Nominal ratings			
Camera			
Туре		CMOS , Global shutter	
Number of pixels		752 x 480 pixels	
Gray scale		256	
Functional safety related parar	neters		
MTTF _d		20 a	
Mission Time (T _M)		10 a	
Diagnostic Coverage (DC)		0 %	
Indicators/operating means			
Operation indicator		LED green: Ready for operation	
Function indicator		7 LEDs (communication, alignment aid, status information)	
Control elements		Button for parameterization	
Electrical specifications			
Operating voltage	U_B	24 V DC +/- 15 %, PELV	
No-load supply current	I ₀	max. 400 mA	
Power consumption	P_0	6 W	
Interface			
Interface type		100 BASE-TX PROFINET	
Protocol		PROFINET IO Real-Time (RT) Conformance class A	
Transfer rate		100 MBit/s	
Standard conformity			
Noise immunity		EN 61000-6-2:2005	
Ambient conditions			
Operating temperature		0 60 °C (32 140 °F) , $$ -20 60 °C (-4 140 °F) (noncondensing; prevent icing on the lens!)	
Storage temperature		-30 85 °C (-22 185 °F)	
Relative humidity		90 % , noncondensing	
Mechanical specifications			
Degree of protection		IP67	
Material			
Housing		PC/ABS	
Optical face		Plastic pane	
Installation		4 x M6 threading	
Mass		approx. 200 g	

Approvals and certificates

cULus Listed, General Purpose, Class 2 Power Source **UL** approval CCC approval CCC approval / marking not required for products rated ≤36 V Approvals CE

Curves / Diagrams



Accessories

V19-G-5M-PUR-ABG

Female cordset, M12, 8-pin, shielded, PUR cable

V1SD-G-2M-PUR-ABG-V1SD-G

Ethernet bus cable, M12 to M12, PUR cable 4-pin, CAT5e

V1SD-G-5M-PUR-ABG-V1SD-G

Ethernet bus cable, M12 to M12, PUR cable 4-pin, CAT5e

PCV-MB1

Mounting bracket for PCV* read head

PCV-SC12A

Grounding clip for PCV system

PCV-SC12

Grounding clip for PCV system

V19-G-10M-PUR-ABG

Female cordset, M12, 8-pin, shielded, PUR cable

V19-G-2M-PUR-ABG

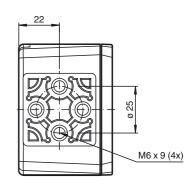
Female cordset, M12, 8-pin, shielded, PUR cable

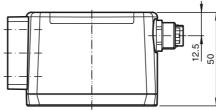
Other suitable accessories can be found at www.pepperl-fuchs.com

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General

The PHA... Vision Sensor has been developed for the rack fine positioning of stock feeders. This device detects circular holes in the rack structure and determines the position deviation of these holes in relation to the target position. The Vision Sensor operates in two dimensions.

Mounting and Commissioning

Mount the PHA... Vision Sensor in such a way that the optical surface of the device captures the optimum distance to the carrier/hole (see "Technical Data"). The stability of the Vision Sensor mounting and the manner in which the vehicle is guided must ensure that the device is not operated outside of its depth of focus range.

All Vision Sensors can be adapted to optimally meet specific requirements by means of parameterization.

Indicators and Controls

The PHA... Vision Sensor is equipped with seven indicator LEDs for carrying out visual function checks and rapid diagnostics. The read head is equipped with two buttons at the back for activating the parameterization mode.

LEDs

LED	Color	Labeling	Meaning
1	yellow	BUS LINK	PROFINET communication active
2	yellow	BUS TX / RX	Data transfer
3	red	BUS ERR	PROFINET communication error
4	green/red	PWR/ERR	Fault with power supply/general error
5	yellow	ZERO POS	Zero position reached
6	yellow	RANGE	Within detection/capture range
7	red/green/yellow	INTERNAL DIAGNOSTIC	Internal diagnostics

External Parameterization

In order to parameterize the device externally, the parameterization code is required in the form of a data matrix containing the desired parameters. Data matrix code cards detailing the step-by-step process for externally parameterizing the device are printed in the operating instructions for the Vision Sensor.

- The Vision Sensor is switched over from normal operation to parameterization mode using button 2 on the back of the device. To switch the device over, button 2 must be pressed and held for more than two seconds. LED5 then flashes.
 - **Note:** Parameterization mode is exited automatically if the device is inactive for one minute. In this case, the Vision Sensor reverts to normal mode and operates without the settings having been changed.
- Place the parameterization code in the field of vision of the camera module. After the parameterization code is detected, the green LED4 lights up for one second. In the event of an invalid parameterization code, LED4 lights up red for two seconds.
- Briefly pressing button 2 will end parameterization mode. Unsaved changes will be lost.