









#### **Model Number**

#### **DVS58**

#### **Features**

- Industrial standard housing Ø58 mm
- 16 Bit singleturn
- Galvanically isolated DeviceNet interface
- Servo or clamping flange

## **Description**

In addition to the CANopen, PROFIBUS and AS-Interface rotary encoders, we have broadened our product line of bus-capable absolute encoders with the DVS58 for DeviceNet.

Absolute encoders deliver an absolute step value for each angle setting. All these values are represented by code samples of one or more code disks. The code disks are screened by an infrared LED and the bit obtained sample is detected by means of an optical array. Its signals are electronically amplified and are forwarded on to the interface for processing.

The absolute encoder has a maximum basic resolution of 65536 steps per revolution (16 Bits). The integrated CAN bus interface of the absolute encoder supports all DeviceNet functions. The following operating modes can be programmed, and can selectively be turned on or off:

- Polled mode
- Cyclic Mode
- Change of state mode

The device is designed for shaft mounting and is available in servo flange or clamping flange design.

# Technical data General specifications

| a chichai checimeanene               |                             |
|--------------------------------------|-----------------------------|
| Detection type                       | photoelectric sampling      |
| Device type                          | Singleturn absolute encoder |
| Functional safety related parameters |                             |

 $\begin{array}{lll} \text{MTTF}_{\text{d}} & \text{80 a} \\ \text{Mission Time } (\text{T}_{\text{M}}) & \text{20 a} \\ \text{1.0 F} \end{array}$ 

L<sub>10</sub> 1.9 E+11 at 6000 rpm and 20/40 N axial/radial shaft load Diagnostic Coverage (DC) 0 %

Electrical specifications Operating voltage  $U_B$  10 ... 30 V DC

No-load supply current I<sub>0</sub> max. 230 mA at 10 V DC max. 100 mA at 24 V DC

Time delay before availability  $t_v$  < 250 ms Linearity  $\pm$  2 LSB at 16 Bit,  $\pm$  1 LSB at 13 Bit,  $\pm$  0,5 LSB at 12 Bit

Output code binary code
Code course (counting direction) cw ascending (clockwise rotation, code course ascending)

cw descending (clockwise rotation, code course descending)

Interface type DeviceNet
Resolution
Single turn up to 16 Bit

Overall resolution up to 16 Bit
Transfer rate max. 0.5 MBit/s
Connection

Terminal compartment in removable housing cover

Standard conformity
Degree of protection DIN EN 60529, IP65

IP66 (with shaft seal)
Climatic testing DIN EN 60068-2-30 , no moisture condensation

Emitted interference DIN EN 61000-6-4

Ambient conditions
Operating temperature -40 ... 85 °C (-40 ... 185 °F)

Storage temperature  $-40 \dots 85\ ^{\circ}\text{C}\ (-40 \dots 185\ ^{\circ}\text{F})$  Mechanical specifications

Material

Shaft load

Combination 1 housing: powder coated aluminum

flange: aluminum shaft: stainless steel

Combination 2 (Inox) housing: stainless steel flange: stainless steel shaft: stainless steel

Mass approx. 550 g (combination 1) approx. 1000 g (combination 2)

Rotational speed max. 12000 min -1

Moment of inertia

Starting torque

max. 12000 min

30 gcm<sup>2</sup>

Starting torque

≤ 3 Ncm (version without shaft seal)

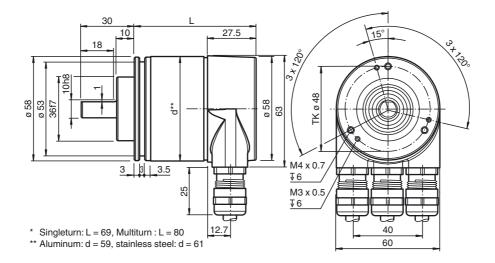
Axial 40 N Radial 110 N

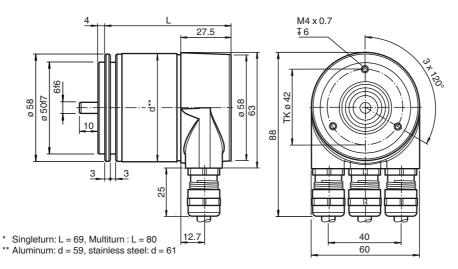
#### Approvals and certificates

UL approval cULus Listed, General Purpose, Class 2 Power Source

Release date: 2017-07-06 13:09 Date of issue: 2017-07-06 t49156\_eng.xml

# **Dimensions**

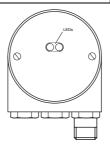




## **Electrical connection**

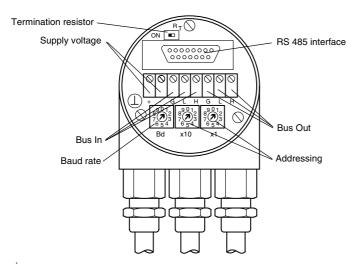
| Terminal | Cable | M12 x 1 Connector | Explanation                        |  |
|----------|-------|-------------------|------------------------------------|--|
| Τ        | -     | -                 | Ground connection for power supply |  |
| (+)      | Red   | 2                 | Power supply                       |  |
| (-)      | Black | 3                 | Power supply                       |  |
| CG       | -     | 1                 | CAN ground                         |  |
| CL       | Blue  | 5                 | CAN low                            |  |
| CH       | White | 4                 | CAN high                           |  |
| CG       | -     | -                 | CAN ground                         |  |
| CL       | Blue  | -                 | CAN low                            |  |
| CH       | White | -                 | CAN high                           |  |

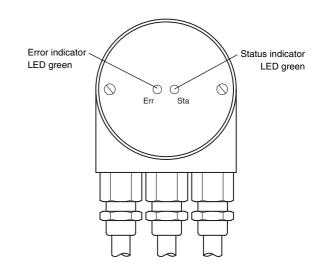




# Indicating and operating elements

2





# Adjusting the participant address

The participant address can be adjusted with the rotary switches. The address can be defined between 1 and 63, and may only be assigned once.



## Adjusting the termination resistor

The terminating resistor  $R_T$  (121  $\Omega$ ) can be connected to the circuit by means of the switch:





## **Baud rate adjustment**

| Baud rate [kBit/s] | Switch position |
|--------------------|-----------------|
| 125                | 0               |
| 250                | 1               |
| 500                | 2               |
| 125                | 3               |
| reserved           | 4 9             |

## **LED-indicators**

| LED red  | LED green | Meaning  |  |
|----------|-----------|--|--|
| off      | off       | No voltage supply  |  |
| off      | on        | Encoder ready, boot-up message not transmitted, yet. Possible reasons: - no further participant present - wrong baud rate - encoder in prepared status |  |
| flashing | on        | Boot-up message transmitted, Device configuration possible.  |  |
| on       | on        | Normal operation mode, encoder in operational status.  |  |

# **Programmable CAN operating modes**

| Mode                 | Explanation  |  |
|----------------------|--|--|
| Polled mode          | The connected host requests the current actual position value via a telegram. The absolute encoder reads in the current position, calculates all parameters that may have been set and then sends back the actual process value.                                   |  |
| Cyclic mode          | The absolute encoder sends the current process value depending on a programmable timer. This can cause the bus load to be reduced since the member on the network only sends a message after a specific amount of time without a prompt from the master.           |  |
| Change of state mode | The absolute encoder monitors the current process value and transfers the current value by itself if there is any change in the value. This can cause the bus load to be reduced, since the member on the network only sends a message if there has been a change. |  |

# Programmable rotary encoder parameters

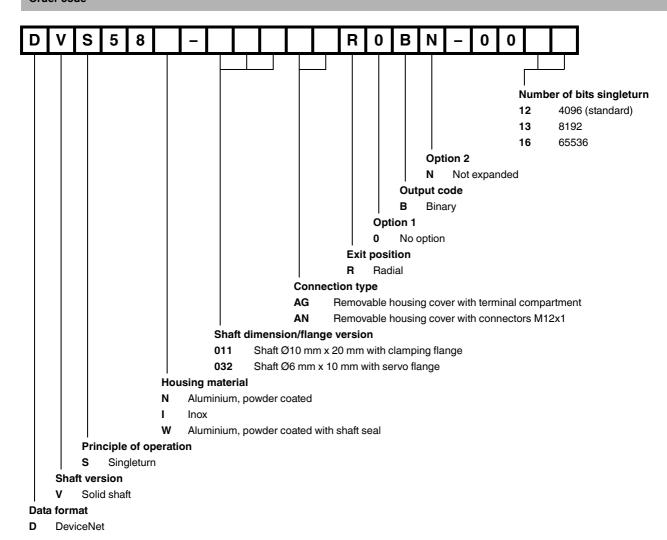
| Parameter  | Explanation |  |  |
|--|-------------|--|--|
| Operating parameter  The direction of rotation (complement) can be specified by parameter as the operating parameter parameter determines the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising or descending the direction of rotation in which the output code will be rising the direction of rotation in which the output code will be reconsistent to the direction of rotation in which the output code will be reconsistent to the direction of rotation in which the output code will be reconsistent to the direction of rotation in which the output code will be reconsistent to the direction of rotation in which the output code will be reconsistent to the direction of rotation of rotation in which the output code will be reconsistent to the direction of rotation of rotation in which the output code will be reconsistent to the direction of rotation of rotation of rotation in which the output code will be reconsistent to the direction of rotation of rotat |             |  |  |
| Resolution per revolution  The "Resolution" parameter is used to program the rotary encoder so that a desired number of st implemented in reference to a revolution.   |             |  |  |
| Preset value  The preset value is the desired position value that must be achieved for a specific physical setting. The preset value parameter is used to set the actual position value to the desired actual process value.   |             |  |  |

## **Accessories**

| For type   | Accessories             | Name/defining feature       | Order code      |
|------------|-------------------------|-----------------------------|-----------------|
|            | Couplings               | D1: Ø10 mm, D2: Ø10 mm      | 9401            |
|            |                         | D1: Ø10 mm, D2: Ø10 mm      | 9404            |
|            |                         | D1: Ø10 mm, D2: Ø10 mm      | 9409            |
|            |                         | D1: Ø10 mm, D2: Ø10 mm      | KW              |
|            |                         | Plastic                     | 9101, 10        |
|            | Measurement wheels with | Pimpled rubber              | 9102, 10        |
| DVS58N-011 | circumference of 500 mm | Knurled aluminium           | 9103, 10        |
| DV330N-011 |                         | Knurled plastic             | 9112, 10        |
|            |                         | Plastic                     | 9108, 10        |
|            | Measurement wheels with | Pimpled rubber              | 9109, 10        |
|            | circumference of 200 mm | Knurled aluminium           | 9110, 10        |
|            |                         | Knurled plastic             | 9113, 10        |
|            | Mounting aids           | Mounting bracket            | 9203            |
|            | Wounting alus           | Mounting bracket            | 9213            |
|            |                         | D1: Ø6 mm, D2: Ø6 mm        | 9401            |
|            | Couplings               | D1: Ø6 mm, D2: Ø6 mm        | 9402            |
|            |                         | D1: Ø6 mm, D2: Ø6 mm        | 9404            |
| DVS58N-032 |                         | D1: Ø6 mm, D2: Ø6 mm        | 9409            |
|            |                         | D1: Ø6 mm, D2: Ø6 mm        | KW              |
|            | Mounting aids           | Mounting bracket and set    | 9300 and 9311-3 |
|            |                         | Eccentric clamping elements | 9310-3          |

For additional information on the accessories, please see the "Accessories" section.

## Order code



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