CE   cULus   CANopen

Model Number

CVS58

Features

- **Industrial standard housing Ø58 mm**
- **Servo or clamping flange**
- **16 Bit singleturn**
- **Galvanically isolated CAN interface**
- **2 limit switches**
- **8 programmable cams**
- **Velocity and acceleration output**
- **Event triggered process data transfer**

Description

Absolute encoders deliver an absolute step value for each angle setting. All these values are represented by code samples on one or more code disks which are sampled by a photoelectric array.

The absolute encoder has a maximum basic resolution of 65536 steps per revolution (16 Bits).

The encoders integrated CAN bus interface supports all CANopen functions. The following operating modes can be programmed, and can be selectively turned on or off:

- Polled mode
- Cyclic mode
- Sync mode

The device is designed for shaft assembly and is available in servo flange or clamping flange design. The bus electronics module is integrated into the removable housing cover. This makes it possible to mount or replace the encoder and the bus electronics separately during installation or service.

Technical data

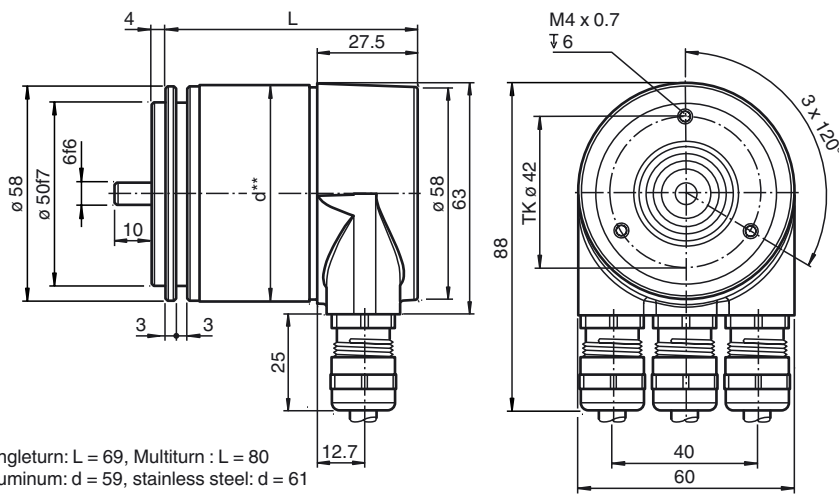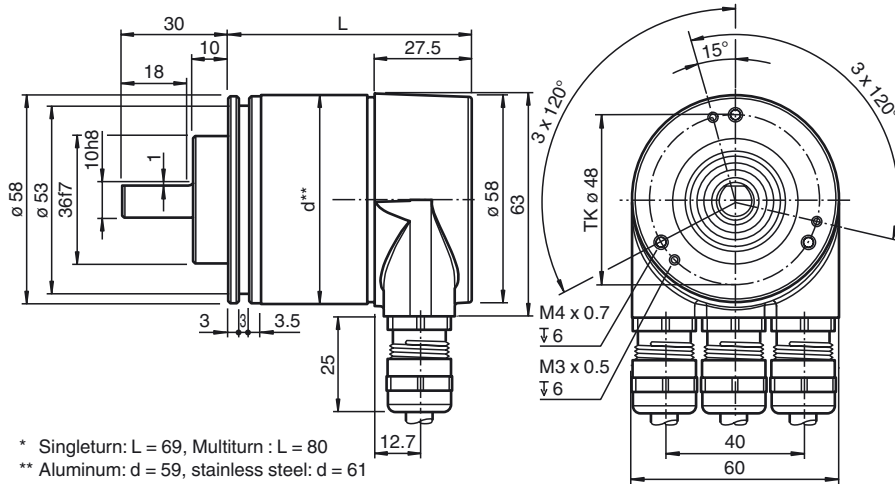| General specifications	
Detection type	photoelectric sampling
Device type	Singleturn absolute encoder
Functional safety related parameters	
$MTTF_d$	80 a
Mission Time (T_M)	20 a
L_{10}	1.9 E+11 at 6000 rpm and 20/40 N axial/radial shaft load
Diagnostic Coverage (DC)	0 %
Electrical specifications	
Operating voltage U_B	10 ... 30 V DC
No-load supply current I_0	max. 350 mA
Time delay before availability t_v	< 250 ms
Linearity	± 2 LSB at 16 Bit, ± 1 LSB at 13 Bit, ± 0,5 LSB at 12 Bit
Output code	binary code
Code course (counting direction)	cw ascending (clockwise rotation, code course ascending) cw descending (clockwise rotation, code course descending)
Interface	
Interface type	CANopen
Resolution	
Single turn	up to 16 Bit
Overall resolution	up to 16 Bit
Transfer rate	max. 1 MBit/s
Standard conformity	communication profile: DS 301 Device profiles: DS 406 and DS 417 , programmable according to class 2
Connection	
Terminal compartment	in removable housing cover
Standard conformity	
Degree of protection	DIN EN 60529, IP65 IP66 (with shaft seal)
Climatic testing	DIN EN 60068-2-30 , no moisture condensation
Emitted interference	EN 61000-6-4:2007
Noise immunity	EN 61000-6-2:2005
Shock resistance	DIN EN 60068-2-27, 100 g, 6 ms
Vibration resistance	DIN EN 60068-2-6, 20 g, 10 ... 2000 Hz
Ambient conditions	
Operating temperature	-40 ... 85 °C (-40 ... 185 °F)
Storage temperature	-40 ... 85 °C (-40 ... 185 °F)
Mechanical specifications	
Material	
Combination 1	housing: powder coated aluminum flange: aluminum shaft: stainless steel
Combination 2 (Inox)	housing: stainless steel flange: stainless steel shaft: stainless steel
Mass	approx. 550 g (combination 1) approx. 1100 g (combination 2)
Rotational speed	max. 12000 min^{-1}
Moment of inertia	30 gcm^2
Starting torque	≤ 3 Ncm (version without shaft seal)
Shaft load	
Axial	40 N
Radial	110 N

Approvals and certificates	
UL approval	cULus Listed, General Purpose, Class 2 Power Source

Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

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Dimensions

* Singleturn: L = 69, Multiturn : L = 80
** Aluminum: d = 59, stainless steel: d = 61

* Singleturn: L = 69, Multiturn : L = 80
** Aluminum: d = 59, stainless steel: d = 61

Electrical connection

Terminal	Cable	Explanation
⊥	-	Ground connection for power supply
(+)	Red	Power supply
(-)	Black	Power supply
G	-	CAN ground
L	Blue	CAN low
H	White	CAN high
G	-	CAN ground
L	Blue	CAN low
H	White	CAN high

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Indicating and operating elements

Termination resistor
Supply voltage
RS 485 interface
Bus In
Bus Out
Baud rate
Addressing
Bd x10 x1

Error indicator LED red
Status indicator LED green
Err Run
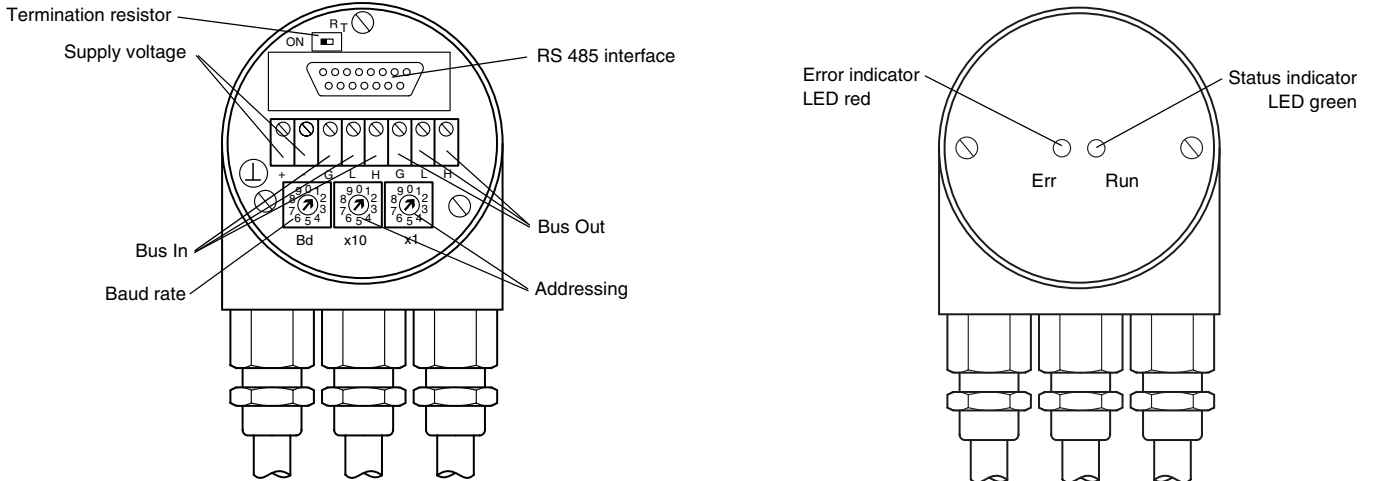
Adjusting the participant address

The participant address can be adjusted with the rotary switches. The address can be defined between 1 and 96, and may only be assigned once. The addresses 97 ... 99 are reserved.

x10   x1
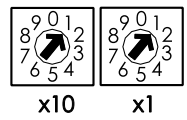
Adjusting the termination resistor

The terminating resistor R_T (121 Ω) can be connected to the circuit by means of the switch:

member X

last participant

ON R_T

ON R_T

Baud rate adjustment

Baud rate [kBit/s]	Switch position	Baud rate [kBit/s]	Switch position
20	0	500	5
50	1	800	6
100	2	1000	7
125	3	reserved	8
250	4	set baud rate by SDO message and LSS	9

LED-indicators

CAN Run (green)	State	Description
flickering	AutoBitrate / LSS	Auto-bitrate detection is in progress or LSS services are in progress
blinking	PREOPERATIONAL	Encoder is in state PREOPERATIONAL
single flash	STOPPED	Encoder is in state STOPPED
double flash		reserved
triple flash	Program / Firmware download	a software download is running on the encoder
on	OPERATIONAL	the encoder is in state OPERATIONAL

Err (red)	State	Description
off	no error	the encoder is in working condition
flickering	AutoBitrate / LSS	Auto-bitrate detection is in progress or LSS services are in progress
blinking	invalid configuration	general configuration error
single flash	Warning limit reached	at least one of the error counters of the CAN controller has reached or exceeded the warning level (too many error frames)
double flash	Error control event	a guard event (NMT-slave or NMT-master) or a heartbeat event (heartbeat consumer) has occured
triple flash	Sync. error	the sync. message has not been received within the configured communication cycle period time out (see objekt 1006h)
quadruple flash	Error, event-timer	an expected PDO has not been received before the even-timer elapsed
on	Bus off	the CAN controller is bus off

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Programmable CAN operating modes

Mode	Explanation
Polled mode	The connected host requests the current actual position value via a remote transmission request telegram. The absolute encoder reads in the current position, calculates all parameters that have been set and sends back the process actual value through the same CAN identifier.
Cyclic mode	The absolute encoder sends the current actual process value cyclically, without being prompted by the host. The cycle time can be programmed in milliseconds for values between 1 ms and 65536 ms.
Sync mode	After the sync telegram has been received by the host, the absolute encoder sends the current actual process value. If multiple nodes should respond to the sync telegram, the individual nodes report one after the other according to their CAN identifier. There is no programming of an offset time. The sync counter can be programmed so that the rotary encoder does not transmit until after a defined number of sync telegrams.

Programmable rotary encoder parameters

Parameter	Explanation
Operating parameter	The direction of rotation (complement) can be specified by parameter as the operating parameter. This parameter determines the direction of rotation in which the output code will ascend or descend.
Resolution per revolution	The "Resolution" parameter is used to program the rotary encoder so that a desired number of steps can be implemented in reference to one revolution.
Preset value	The preset value is the desired position value that must be achieved for a specific physical setting of the axis. The preset value parameter is used to set the actual position value to the desired actual process value.
2 limit switches	A total of two positions can be programmed. The absolute encoder sets one bit to high state in the 32 Bit actual process value if a value falls outside the range between these two positions.
8 cam switches	Up to 8 position values can be programmed as cams. By reaching these values bits in object 6300h Cam state register are set.

Accessories

For type	Accessories	Name/defining feature	Order code
CVS58N-011	Couplings	D1: Ø10 mm, D2: Ø10 mm	9401
		D1: Ø10 mm, D2: Ø10 mm	9404
		D1: Ø10 mm, D2: Ø10 mm	9409
		D1: Ø10 mm, D2: Ø10 mm	KW
	Measurement wheels with circumference of 500 mm	Plastic	9101, 10
		Pimpled rubber	9102, 10
		Knurled aluminium	9103, 10
		Knurled plastic	9112, 10
	Measurement wheels with circumference of 200 mm	Plastic	9108, 10
		Pimpled rubber	9109, 10
		Knurled aluminium	9110, 10
		Knurled plastic	9113, 10
	Mounting aids	Mounting bracket	9203
		Mounting bracket	9213
CVS58N-032	Couplings	D1: Ø6 mm, D2: Ø6 mm	9401
		D1: Ø6 mm, D2: Ø6 mm	9402
		D1: Ø6 mm, D2: Ø6 mm	9404
		D1: Ø6 mm, D2: Ø6 mm	9409
		D1: Ø6 mm, D2: Ø6 mm	KW
	Mounting aids	Mounting bracket and set	9300 and 9311-3
		Eccentric clamping elements	9310-3

For additional information on the accessories, please see the "Accessories" section.

Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

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Order code

| C | V | S | 5 | 8 | | – | | | | | R | 0 | B | N | – | 0 | 0 | |

Number of bits singleturn
- **12**   4096 (standard)
- **13**   8192
- **16**   65536

Option 2
- **N**   Not expanded

Output code
- **B**   Binary

Option 1
- **0**   No option

Exit position
- **R**   Radial

Connection type
- **AG**   Removable housing cover with terminal compartment
- **AN**   Removable housing cover with connectors M12x1

Shaft dimension/flange version
- **011**   Shaft Ø10 mm x 20 mm with clamping flange
- **032**   Shaft Ø6 mm x 10 mm with servo flange

Housing material
- **N**   Aluminium, powder coated
- **I**   INOX
- **W**   Aluminium, powder coated with shaft seal

Principle of operation
- **S**   Singleturn

Shaft version
- **V**   Solid shaft

Data format
- **C**   CAN bus

Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

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