2D/3D Profile Sensor

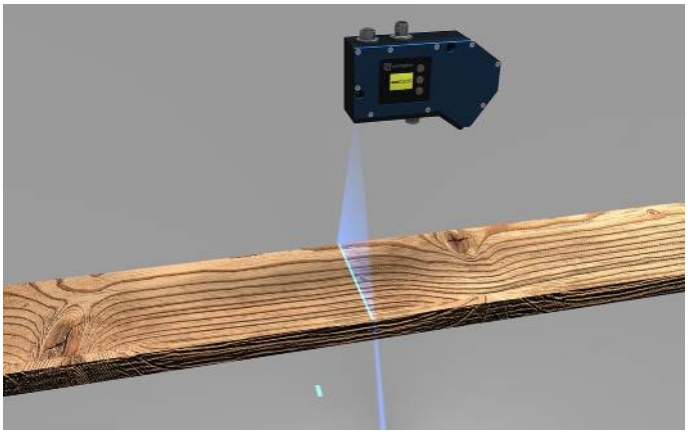
MLWL154 LASER

Part Number

weCat3D

- **Blue light for applications on metal, organic or semi-transparent materials**
- **Increased resistance to extraneous light and high speed**
- **Optimized profile quality thanks to HDR function**
- **Precise measuring range resolution X (> 2000 measuring points)**
- **Up to 12 million measuring points per second**

2D/3D Profile Sensors project a laser line onto the object to be detected and generate an accurate, linearized height profile with an internal camera which is set up at a triangulation angle. Thanks to its uniform, open interface, the weCat3D series can be incorporated by means of the DLL program library or the GigE Vision standard without an additional control unit. Alternatively, wenglor offers its own software packages for implementing your application.



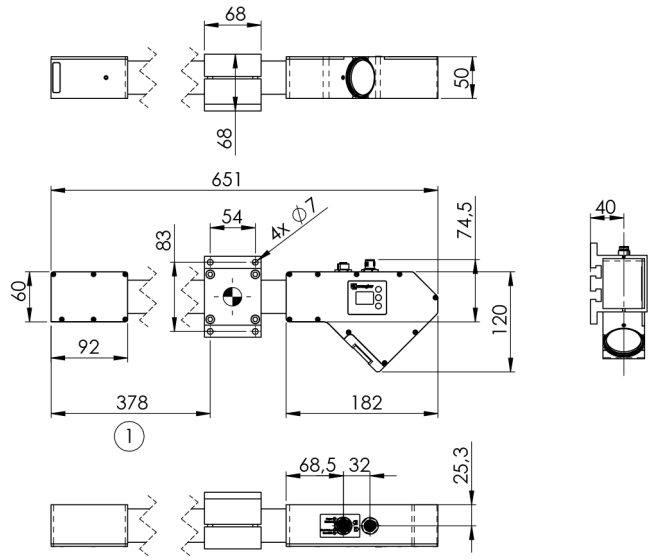
Technical Data

Optical Data	
Working range Z	390...910 mm
Measuring range Z	520 mm
Measuring range X	285...455 mm
Linearity Deviation	130 µm
Resolution Z	17,8...43 µm
Resolution X	151...238 µm
Light Source	Laser (blue)
Wavelength	405 nm
Service Life (T = +25 °C)	20000 h
Laser Class (EN 60825-1)	3R
Max. Ambient Light	5000 Lux
Electrical Data	
Supply Voltage	18...30 V DC
Current Consumption (Ub = 24 V)	300 mA
Measuring Rate	175...6000 /s
Temperature Range	0...45 °C
Storage temperature	-20...70 °C
Inputs/Outputs	4
Switching Output Voltage Drop	< 1,5 V
Switching Output/Switching Current	100 mA
Short Circuit Protection	yes
Reverse Polarity Protection	yes
Overload Protection	yes
Interface	Ethernet TCP/IP
Baud Rate	100/1000 Mbit/s
Protection Class	III
FDA Accession Number	1710276-000
Mechanical Data	
Housing Material	Aluminum
Degree of Protection	IP67
Connection	M12 × 1; 12-pin
Type of Connection Ethernet	M12 × 1; 8-pin, X-cod.
Optic Cover	Glass
Weight	2330 g
Web server	yes
Configurable as PNP/NPN/Push-Pull	●
Switchable to NC/NO	●
Connection Diagram No.	1022 / 1023
Control Panel No.	X2 / A22
Suitable Connection Equipment No.	50 / 87

Display brightness may decrease with age. This does not result in any impairment of the sensor function.

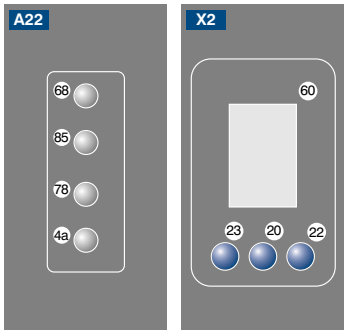
Complementary Products

Control Unit
Cooling Unit ZLWK003
Protective Screen Retainer ZLWS003
Software
Switch ZAC45FN01

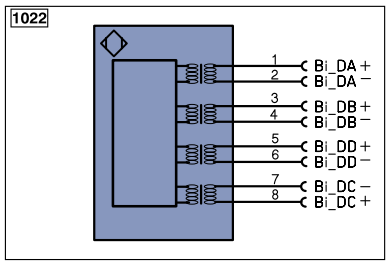


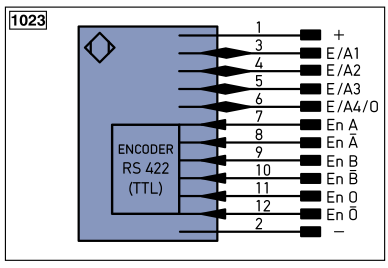
1 = Recommended mounting position based on the sensor's center of gravity
All dimensions in mm (1 mm = 0.03937 Inch)

Ctrl. Panel



20 = Enter Button
22 = UP Button
23 = Down Button
4a = User LED
60 = Display
68 = Supply Voltage Indicator
78 = Module status
85 = Link/Act LED





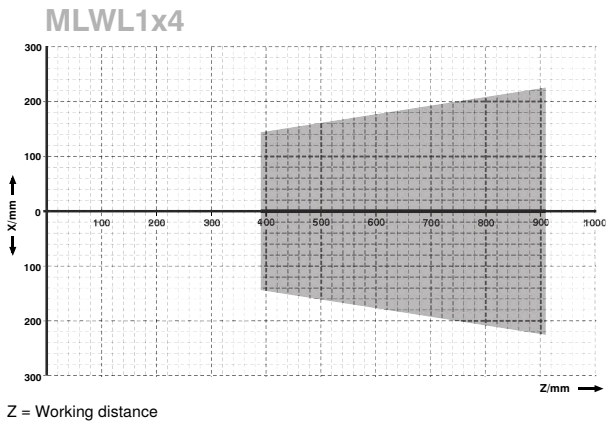
Legend

+	Supply Voltage +
–	Supply Voltage 0 V
~	Supply Voltage (AC Voltage)
A	Switching Output (NO)
Ā	Switching Output (NC)
V	Contamination/Error Output (NO)
V̄	Contamination/Error Output (NC)
E	Input (analog or digital)
T	Teach Input
Z	Time Delay (activation)
S	Shielding
RxD	Interface Receive Path
TxD	Interface Send Path
RDY	Ready
GND	Ground
CL	Clock
E/A	Output/Input programmable
	IO-Link
PoE	Power over Ethernet
IN	Safety Input
OSSD	Safety Output
Signal	Signal Output
Bi_D+/-	Ethernet Gigabit bidirect. data line (A-D)
EN0 RS422	Encoder 0-pulse 0-0̄ (TTL)
PT	Platinum measuring resistor
nc	not connected
U	Test Input
Ū	Test Input inverted
W	Trigger Input
O	Analog Output
O–	Ground for the Analog Output
BZ	Block Discharge
AMV	Valve Output
a	Valve Control Output +
b	Valve Control Output 0 V
SY	Synchronization
E+	Receiver-Line
S+	Emitter-Line
⏚	Grounding
SnR	Switching Distance Reduction
Rx+/–	Ethernet Receive Path
Tx+/–	Ethernet Send Path
Bus	Interfaces-Bus A(+)/B(–)
La	Emitted Light disengageable
Mag	Magnet activation
RES	Input confirmation
EDM	Contactor Monitoring
ENA RS422	Encoder A/Ā (TTL)
ENB RS422	Encoder B/B̄ (TTL)
ENA	Encoder A
ENB	Encoder B
AMIN	Digital output MIN
AMAX	Digital output MAX
AOK	Digital output OK
SY In	Synchronization In
SY OUT	Synchronization OUT
OLT	Brightness output
M	Maintenance
rsv	reserved

Wire Colors according to DIN IEC 757

BK	Black
BN	Brown
RD	Red
OG	Orange
YE	Yellow
GN	Green
BU	Blue
VT	Violet
GY	Grey
WH	White
PK	Pink
GNYE	Green/Yellow

Measuring field X, Z



Z = Working distance
X = Measuring Range